

# A Templated C++ Interface for isl

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# Polyhedral Compilation

## Polyhedral Compilation

Analyzing and/or transforming programs using the *polyhedral model*

## Polyhedral Model

Abstract representation of a program

- instance based
  - ⇒ statement *instances*
  - ⇒ array *elements*
- compact representation based on polyhedra or similar objects
  - ⇒ integer points in unions of parametric polyhedra
  - ⇒ Presburger sets and relations
- parametric
  - ⇒ description may depend on constant symbols

# Polyhedral Model

Typical constituents of program representation

- Instance Set
  - ⇒ the set of all statement instances
- Access Relations
  - ⇒ the array elements accessed by a statement instance
- Dependences
  - ⇒ the statement instances that depend on a statement instance
- Schedule
  - ⇒ the relative execution order of statement instances

## Illustrative Example: Matrix Multiplication

```
for (int i = 0; i < M; i++)
    for (int j = 0; j < N; j++) {
S1:   C[i][j] = 0;
        for (int k = 0; k < K; k++)
S2:       C[i][j] = C[i][j] + A[i][k] * B[k][j];
    }
```

- Instance Set (set of statement instances)

$$\{ S1[i,j] : 0 \leq i < M \wedge 0 \leq j < N; S2[i,j,k] : 0 \leq i < M \wedge 0 \leq j < N \wedge 0 \leq k < K \}$$

- Access Relations (accessed array elements;  $W$ : write,  $R$ : read)

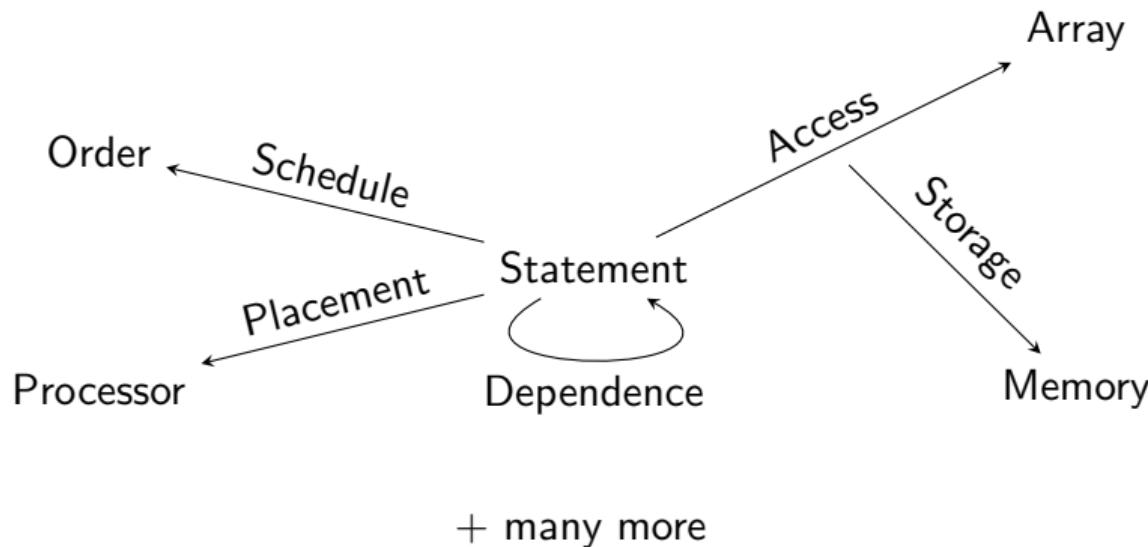
$$W = \{ S1[i,j] \rightarrow C[i,j]; S2[i,j,k] \rightarrow C[i,j] \}$$

$$R = \{ S2[i,j,k] \rightarrow C[i,j]; S2[i,j,k] \rightarrow A[i,k]; S2[i,j,k] \rightarrow B[k,j] \}$$

- Schedule (relative execution order)

$$\{ S1[i,j] \rightarrow [i,j,0,0]; S2[i,j,k] \rightarrow [i,j,1,k] \}$$

# Polyhedral Objects



# Polyhedral Compiler

A sufficiently advanced polyhedral compiler needs to handle many kinds of polyhedral objects

This can cause confusion:

- exactly what kind of object does this function expect?
- does this operation on these objects make sense?

In statically typed languages (such as C++)

⇒ use **types**

What types are available in

- PolyLib (Wilde 1993),
- Omega (Kelly et al. 1996) and
- isl (V. 2010)?

## Types Offered by Polyhedral Libraries: PolyLib

In **PolyLib**, every set or binary relation is represented by a **Polyhedron**.

- ⇒ no differentiation at compile time
- ⇒ even at run time, only dimensionality can be checked

Does it make sense to intersect these two objects?

$$\begin{array}{ccccc} 4 & 5 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & -1 & 0 & 1 & -1 \\ 1 & 0 & -1 & 1 & -1 \end{array}$$
$$\begin{array}{ccccc} 1 & 5 \\ 0 & 1 & -1 & 0 & 0 \end{array}$$

# Types Offered by Polyhedral Libraries: Omega

In **Omega**, every set or binary relation is represented by a [Relation](#).

- ⇒ no differentiation at compile time
- ⇒ at run time, differentiation between tuple size(s) as well as between
  - ▶ sets

```
{ [i, j] : 0 <= i < n and 0 <= j < n }
```

- ▶ binary relations

```
{ [i] -> [i] }
```

## Types Offered by Polyhedral Libraries: `isl` (plain C++)

In `isl`, every set is represented by an `isl::set` or an `isl::union_set` and every binary relation is represented by an `isl::map` or an `isl::union_map`.

- ⇒ differentiation between sets and binary relations at compile time
- ⇒ at run time, differentiation between tuple size(s) and tuple name(s)  
(for `isl::set` and `isl::map`)

```
{ S2[i, j, k] : 0 <= i < M and 0 <= j < N and 0 <= k < K }  
{ S1[i, j] -> C[i, j] }
```

`isl::union_set` and `isl::union_map` objects may contain elements with different tuple sizes and/or names.

```
{ S1[i, j] -> C[i, j]; S2[i, j, k] -> C[i, j] }
```

- ⇒ no run-time checks
- ⇒ still maps *statement instances* to *array elements*
- ⇒ need for more fine-grained types

# Design Goals

- differentiation between different kinds of sets and binary relations
  - ⇒ detect problems such as
    - ▶ access relation passed to function expecting dependence relation
    - ▶ range of access relation intersected with statement instances
- at compile time
- application specific
  - ⇒ `isl` provides general framework
  - ⇒ application defines concrete types
- compatible with plain C++ interface
  - ⇒ allow gradual transition to templated interface
- easy to use
  - ⇒ no annotations beyond what is strictly required

## Basic Idea: Template Types

- Introduce template type for each plain type involving tuples
  - ⇒ same name
  - ⇒ different name space: `isl::typed`
- Every type has 0 or more template parameters, one for each tuple, specifying tuple *kind*

```
template <>
struct set<> : public isl::set { /* ... */ }
```

⇒ constraints on constant symbols, e.g., `{ : M, N, K > 0 }`

```
template <typename Domain>
struct set<Domain> : public isl::set { /* ... */ }
```

⇒ for example: `struct ST {};` `isl::typed::set<ST>;`

```
template <typename Domain, typename Range>
struct map<Domain, Range> : public isl::map { /* ... */ }
```

⇒ for example: `struct AR {};` `isl::typed::map<ST, AR>;`

## Basic Idea: Template Types

- Every type has 0 or more template parameters, one for each tuple, specifying tuple *kind*

```
template <>
struct set<> : public isl::set { /* ... */ }
```

⇒ constraints on constant symbols, e.g.,  $\{ : M, N, K > 0 \}$

```
template <typename Domain>
struct set<Domain> : public isl::set { /* ... */ }
```

⇒ for example: struct ST {}; isl::typed::set<ST>;

```
template <typename Domain, typename Range>
struct map<Domain, Range> : public isl::map { /* ... */ }
```

⇒ for example: struct AR {}; isl::typed::map<ST, AR>;

- ▶ Template type derived from plain type for interoperability
- ▶ Constructor is private to avoid bypassing checks
- ▶ Template argument corresponds to *kind* of tuple (e.g., statement, array), not specific tuple name/size

## Basic Idea: Template Types

```
#include <isl/typed_cpp.h>

struct ST {};
struct AR {};

void f(const isl::typed::union_map<ST, AR> &access);
void g(const isl::typed::union_map<ST, ST> &dep);
void h(const isl::typed::union_map<ST, AR> &access) {
    f(access);
    g(access);
}
```

clang error:

```
error1.cc:10:2: error: no matching function for call to 'g'
      g(access);
      ^
error1.cc:6:6: note: candidate function not viable: no known
      ↪ conversion from 'const union_map<[...], AR>' to 'const
      ↪ union_map<[...], ST>' for 1st argument
void g(const isl::typed::union_map<ST, ST> &dep);
```

## Basic Idea: Template Methods

- Introduce template method for each plain method taking and/or returning objects involving tuples
- Shared template parameter for shared tuple kind

```
template <typename Domain, typename Range>
struct map<Domain, Range> : public isl::map {
    /* ... */
    inline typed::map<Domain, Range> intersect_domain(
        const typed::set<Domain> &set) const;
    inline typed::map<Domain, Range> intersect_range(
        const typed::set<Range> &set) const;
    template <typename Range2>
    inline typed::map<Domain, Range2> apply_range(
        const typed::map<Range, Range2> &map2) const;
}
```

⇒ exploit template argument deduction

## Basic Idea: Template Methods

```
#include <isl/typed_cpp.h>

struct ST {};
struct AR {};

void h(const isl::typed::union_map<ST, AR> &access,
       const isl::typed::union_set<ST> instances) {
    access.intersect_domain(instances);
    access.intersect_range(instances);
}
```

clang error:

```
error2.cc:9:9: error: no matching member function for call to '
    ↪ intersect_range'
        access.intersect_range(instances);
        ~~~~~~
```

```
isl/typed_cpp.h:10731:42: note: candidate function not viable: no
    ↪ known conversion from 'const union_set<ST>' to 'const union_set
    ↪ <AR>' for 1st argument
inline typed::union_map<Domain, Range> intersect_range(const typed
```

## Further Specializations

Consider storage map (from access to memory)

```
{ [S2[i, j, k] -> C[i, j]] -> Mem_C[i, j] }
```

(S2[i, j, k] and C[i, j] are nested tuples in domain tuple)

How to extract mapping from statement to memory { S2[i, j, k] -> Mem\_C[i, j] }?

⇒ `isl::map::domain_factor_domain`

Corresponding template method cannot be made available in `map<Domain, Range>`

⇒ Domain not specific enough

⇒ deleted from `map<Domain, Range>`

⇒ included in more specific specialization

```
template <typename Domain, typename Range, typename Range2>
struct map<pair<Domain, Range>, Range2> : public isl::map {
    /* ... */
    inline typed::map<Domain, Range2> domain_factor_domain() const
}
```

## Explicit Template Arguments: “Constructors”

Consider `isl::set::universe`

⇒ construct a universe `isl::set` from a description of the tuple (specified by an `isl::space`)

```
template <typename Domain>
struct set<Domain> : public isl::set {
    static inline typed::set<Domain> universe(
        const typed::space<Domain> &space);
}
```

Use:

```
void f(const isl::typed::space<ST> &space) {
    auto set = isl::typed::set::universe<ST>(space);
}
```

⇒ both type and template arguments need to be spelled out explicitly

## Explicit Template Arguments: “Constructors”

```
void f(const isl::typed::space<ST> &space) {  
    auto set = isl::typed::set::universe<ST>(space);  
}
```

⇒ both type and template arguments need to be spelled out explicitly

Introduce alternative name `isl::space::universe_set`

```
template <typename Domain>  
struct space<Domain> : public isl::space {  
    inline typed::set<Domain> universe_set() const;  
}
```

Use:

```
void f(const isl::typed::space<ST> &space) {  
    auto set = space.universe_set();  
}
```

## Explicit Template Arguments: Set Range Tuple

`isl::map::set_range_tuple` replaces tuple identifier of range of map

- ⇒ changes meaning of tuple
- ⇒ potentially changes tuple kind
- ⇒ tuple kind needs to be specified explicitly

```
template <typename Domain, typename Range>
struct map<Domain, Range> : public isl::map {
    template <typename Range2>
    inline typed::map<Domain, Range2> set_range_tuple(
        const std::string &id) const;
}
```

⇒ no template argument deduction on Range2

## Template Argument Class Hierarchy

Some specializations may be special cases of other specializations.

- ⇒ allow users to define class hierarchy on template arguments
- ⇒ copy relationship to corresponding template types

For example, user may define a function that takes either array elements or memory elements

- ⇒ derive array and memory template argument from common base class

```
template <typename Domain, typename Range>
struct map<Domain, Range> : public isl::map {
    template <typename Arg1, typename Arg2,
              typename std::enable_if<
                  std::is_base_of<Domain, Arg1>{} &&
                  std::is_base_of<Range, Arg2>{}, bool>::type = true>
    map(const map<Arg1, Arg2> &obj) : isl::map(obj) {}
}
```

# Implementation and Experience

Two “independent” implementations

- ① within the context of Tensor Comprehensions (Vasilache et al. 2019)
  - ▶ external to `isl`
  - ▶ automatically generated from parsed plain C++ headers
- ② within the context of DTG (V. et al. 2020)
  - ▶ part of `isl` (publicly available soon)
  - ▶ automatically generated from parsed C headers

Transition to templated interface benefits from

- automatic type deduction for local variables (`auto`)
- extra local variables to store different kinds of data

- Benefits
- compile-time checks
  - documentation

- Drawbacks
- minor increase in compilation time
  - minor increase in binary size

# Conclusion

Templated C++ interface for isl

- ⇒ compile-time checks using fine-grained, user controlled types
- ⇒ extra information in template arguments allows for checks that were not even available at compile time
- ⇒ available soon

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