

# Optimization Through Recomputation in the Polyhedral Model

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- Related work
- Optimizing Through Recompute
- Polyhedral modelling
- Experimental Results
- Conclusion and future work

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## Introduction

Where innovation starts



### Introduction

- (Mobile) systems use more artificial neural networks
  - Artificial vision
  - Image processing
  - Speech recognition



• Can be improved by code transformations





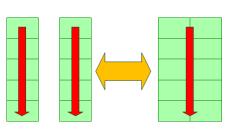


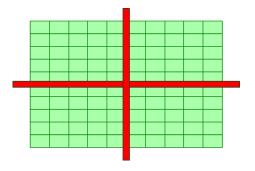


### **Current possibilities and extensions**

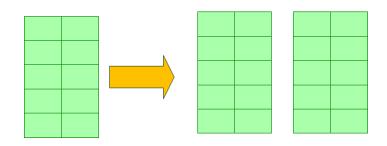
• Tiling

- Fusion
- Distribution





- Recomputation/overlapped tiling
  - Allows for better paralellism
  - Reduces memory traffic





### This paper

- An example CNN application which includes recompute
- Extension of Polly
- Demonstration of the effectiveness of recomputation

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# **Related Work**

#### Where innovation starts



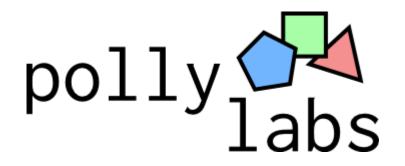
### Automated polyhedral optimization frameworks

- Greatly reduce the effort of translating the original network description into an optimized form
- Automatically verifying the validity
- Different options: Polly, R-Stream-TF, and PPCG
- None of these frameworks provides a method of including recomputation in the optimization space



### Why do we use Polly

- Uses the Polyhedral model for optimizations
- Direct integration with the LLVM compiler framework
- Adjustable
  - Add extra functionality
  - User defined schedules
  - Automate the process



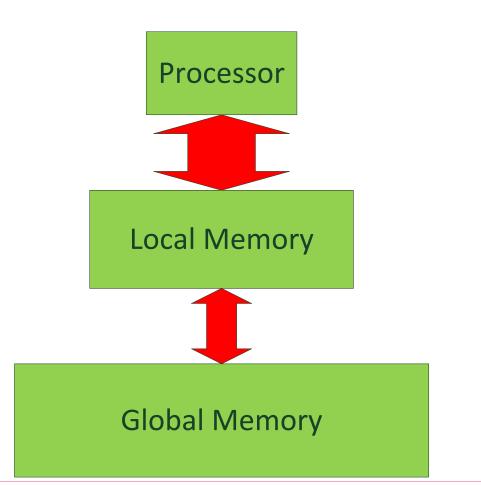
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# Optimizing Through Recompute

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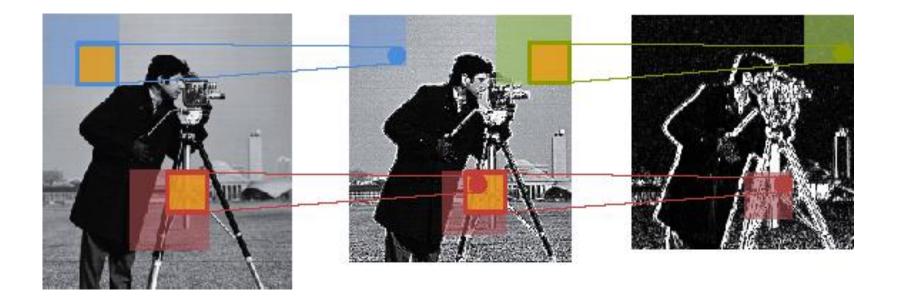


### **System Architecture**

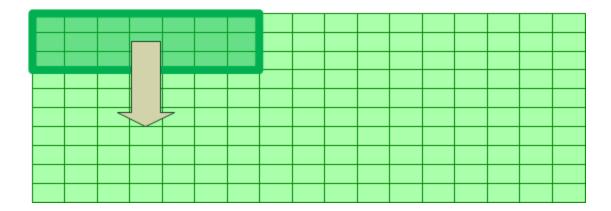




### **Educational Example**

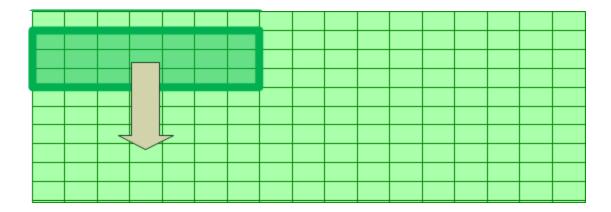






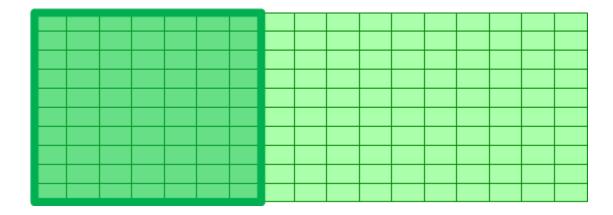
Stored Part of the intermediate image



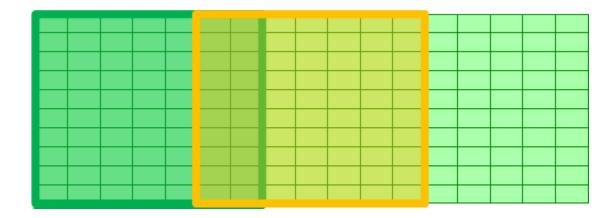


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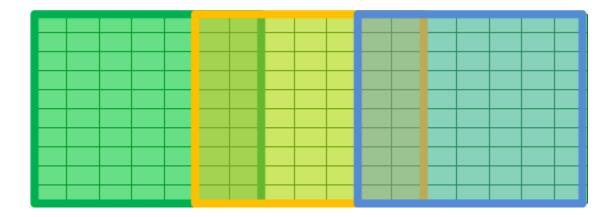








### **Other Dimensions**





### Methods to handle overlap

- Store the overlap globally
- Store the overlap locally
- Recompute the overlap



### **Global Method**

- Pixels are stored externally
- Small buffer size
- Expensive memory accesses



### **Local Method**

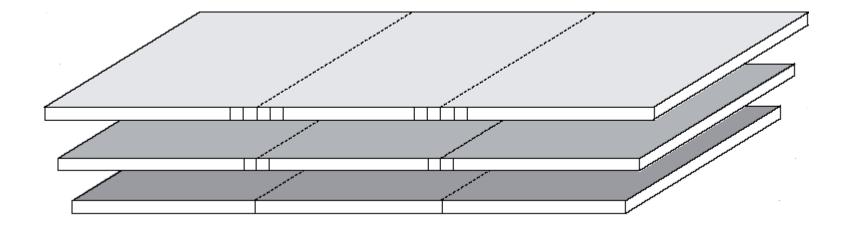
- Pixels are stored locally
- Larger buffers required
- Cheaper accesses



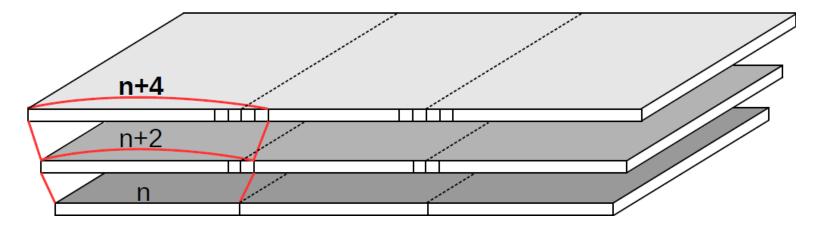
### **Recomputation Method**

- Recomputes the pixels
- No extra memory required
- No extra accesses required
- More computations are required

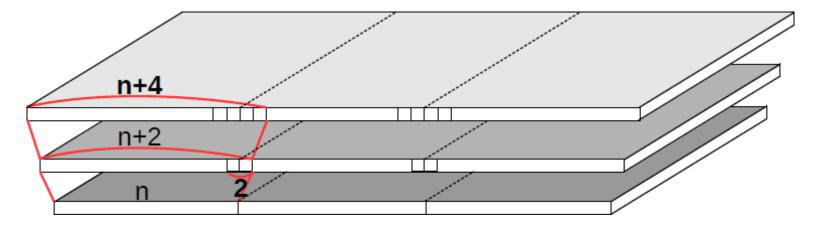




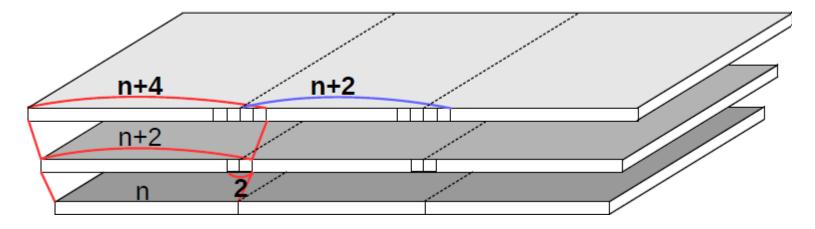




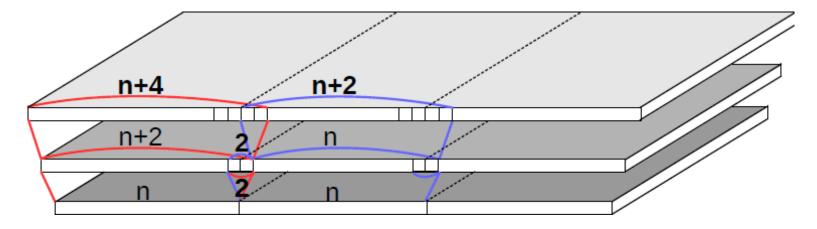




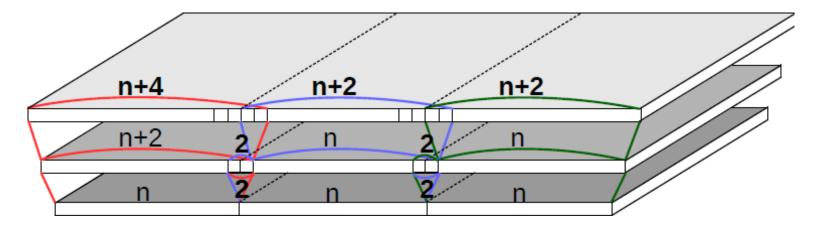




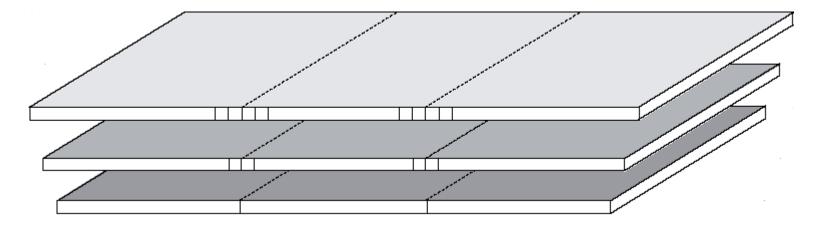




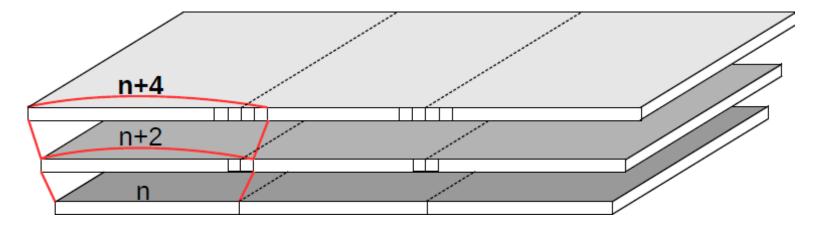




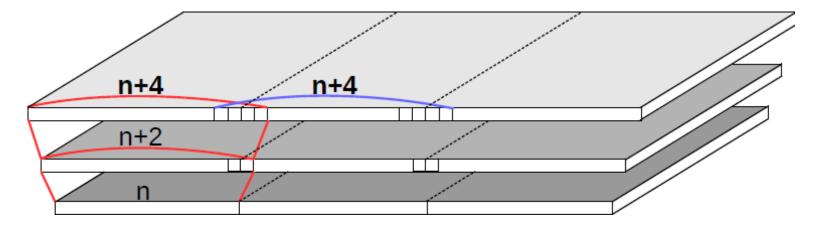




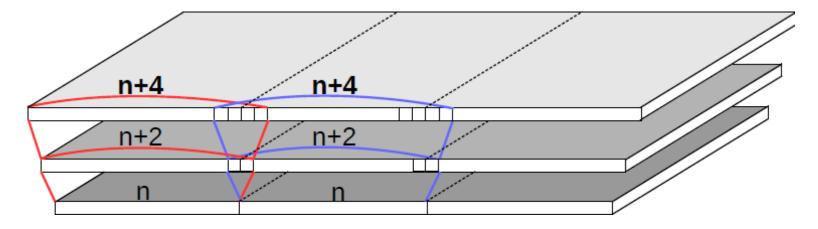




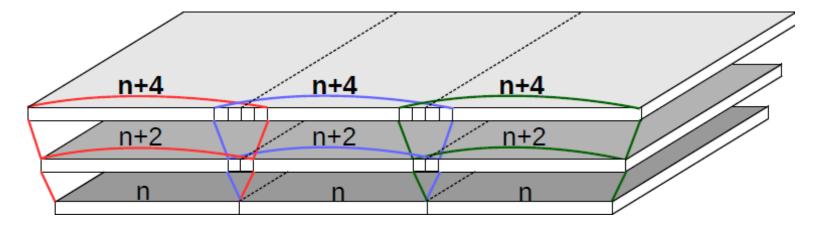




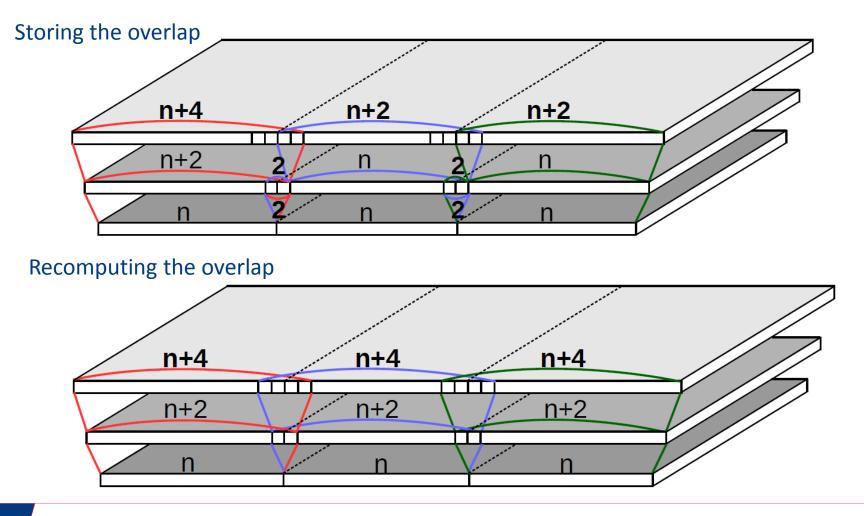












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# Polyhedral Modeling

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#### Where innovation starts



### **The Polyhedral Model and Recomputation**

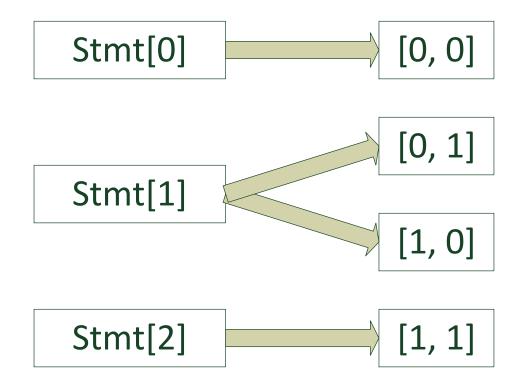
- Execution order is defined by the schedule
- Schedule is singular valued
  - One execution time per statement
  - One statement per execution time
- Recomputation:
  - Statements are executed multiple times
  - Non-singular valued schedules are required



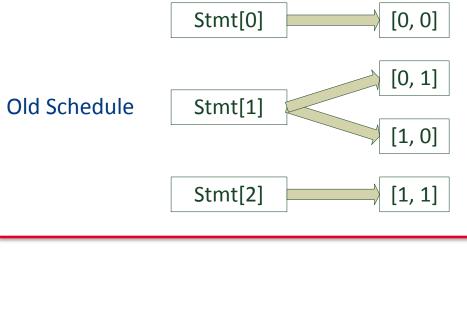
### **Including Recomputation**

- Support for non-singular valued schedules
- Transforming non-singular valued schedules to singular valued schedules



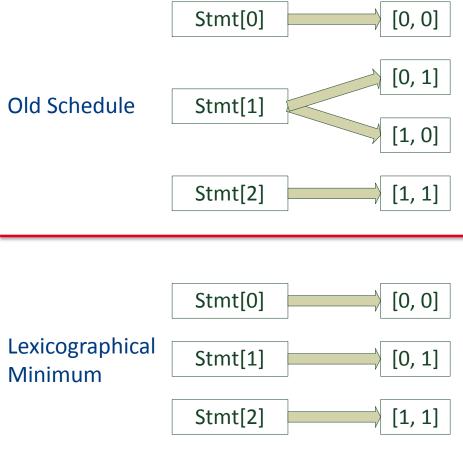






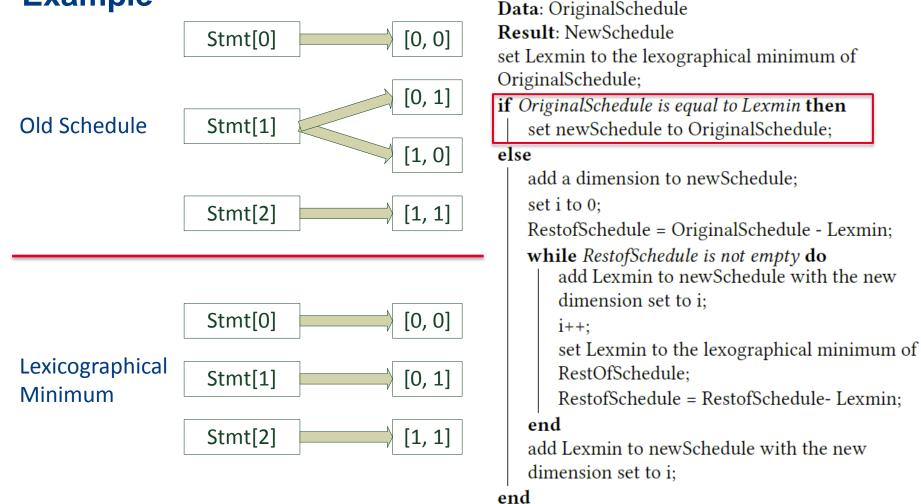
Data: OriginalSchedule Result: NewSchedule set Lexmin to the lexographical minimum of OriginalSchedule; if OriginalSchedule is equal to Lexmin then set newSchedule to OriginalSchedule; else add a dimension to newSchedule; set i to 0; RestofSchedule = OriginalSchedule - Lexmin; while RestofSchedule is not empty do add Lexmin to newSchedule with the new dimension set to i; i++: set Lexmin to the lexographical minimum of RestOfSchedule: RestofSchedule = RestofSchedule- Lexmin; end add Lexmin to newSchedule with the new dimension set to i; end



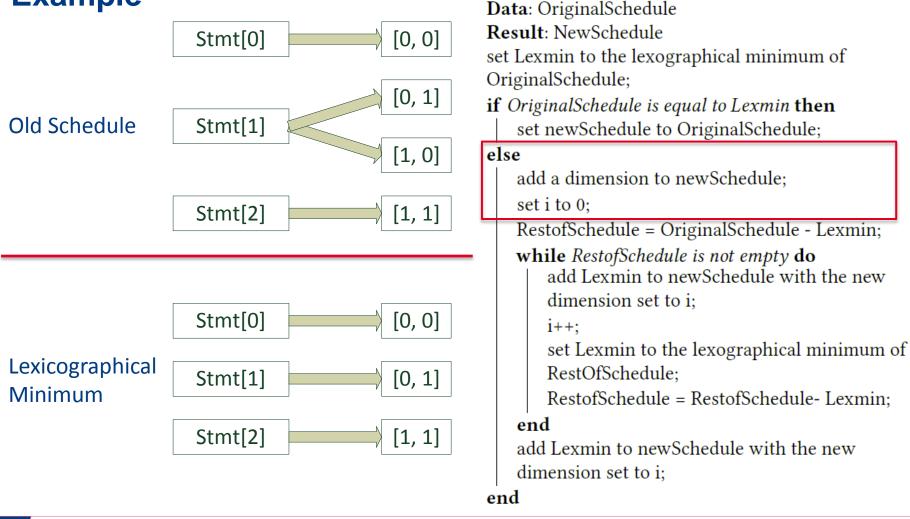


Data: OriginalSchedule									
Result: NewSchedule									
set Lexmin to the lexographical minimum of									
OriginalSchedule;									
if OriginalSchedule is equal to Lexmin then									
set newSchedule to OriginalSchedule;									
else									
add a dimension to newSchedule;									
set i to 0;									
RestofSchedule = OriginalSchedule - Lexmin;									
<ul> <li>while RestofSchedule is not empty do         <ul> <li>add Lexmin to newSchedule with the new             dimension set to i;</li> </ul> </li> </ul>									
i++;									
set Lexmin to the lexographical minimum of RestOfSchedule;									
RestofSchedule = RestofSchedule- Lexmin;									
end									
add Lexmin to newSchedule with the new									
dimension set to i;									
end									

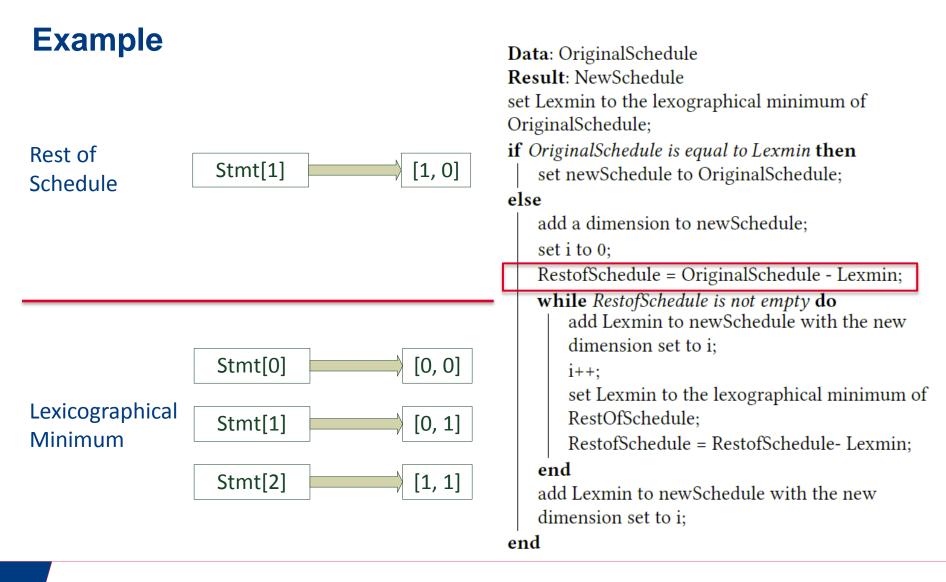




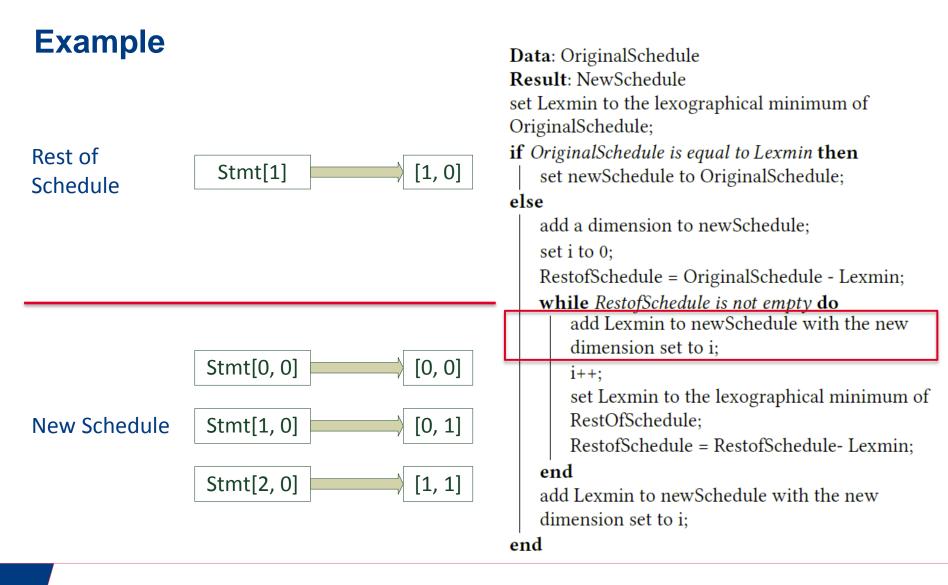




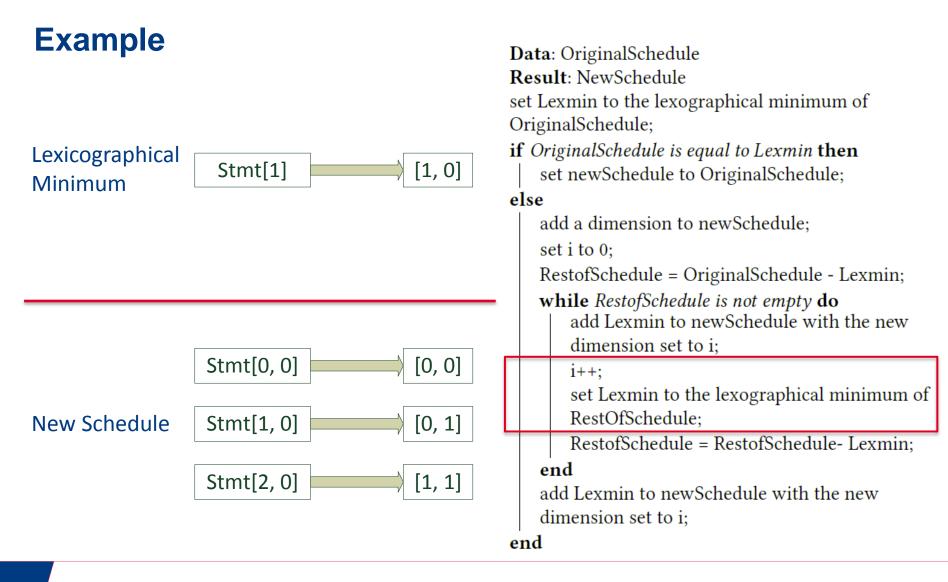




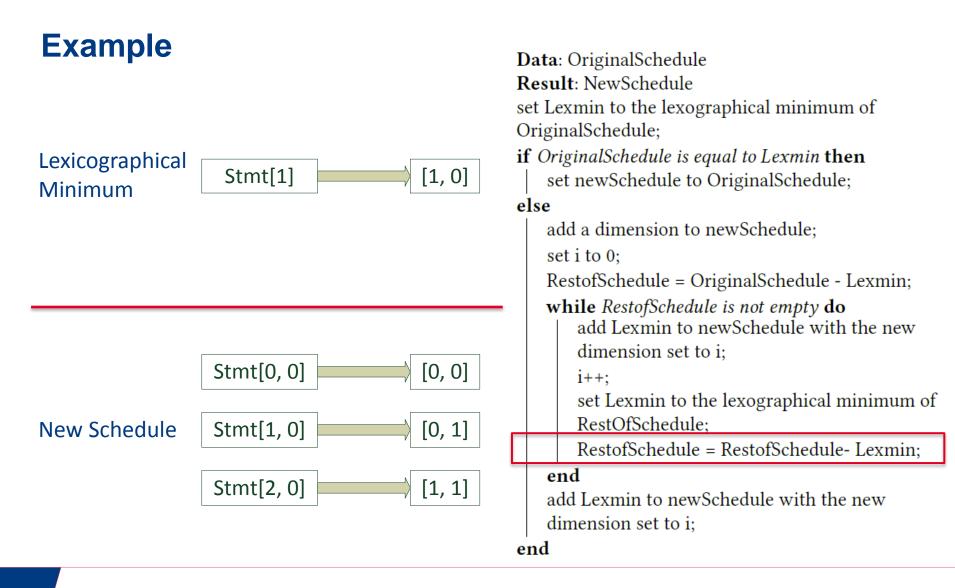




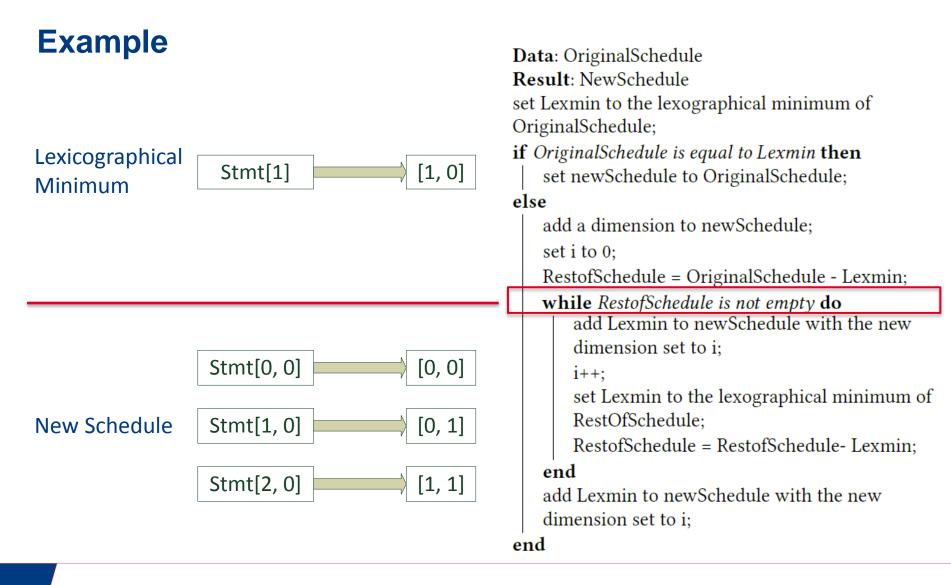






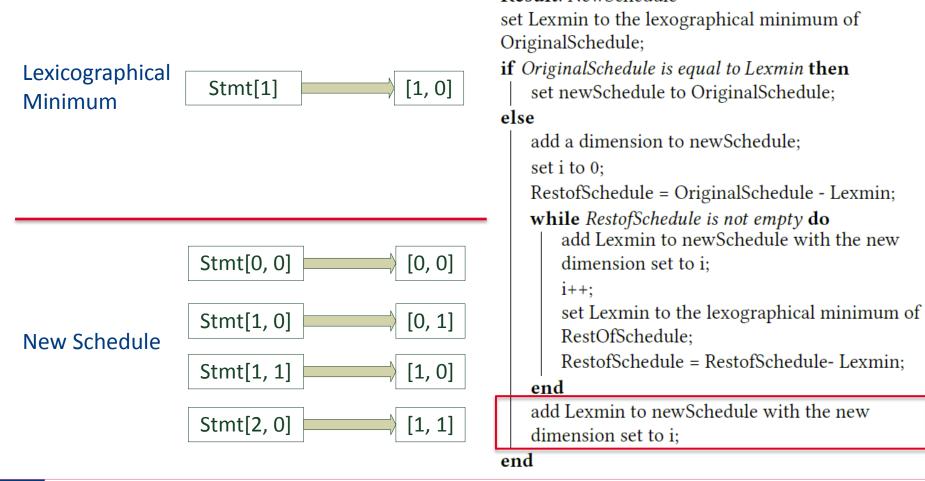










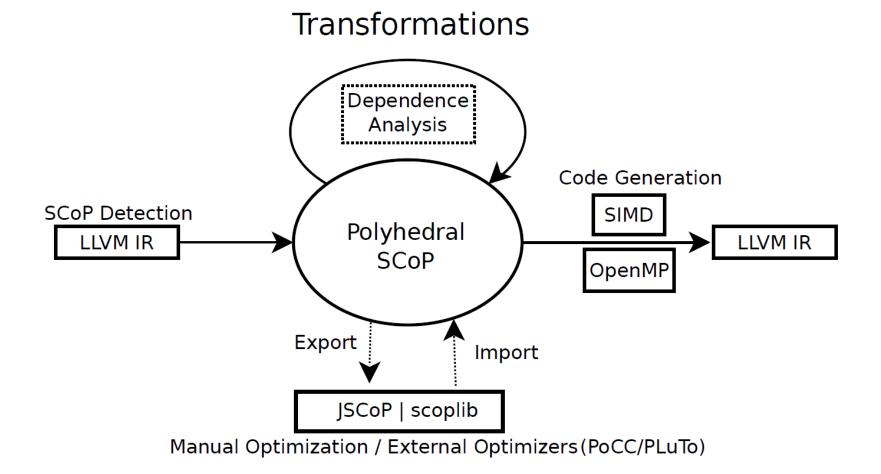


Data: OriginalSchedule Result: NewSchedule





### **Including Recomputation: location**



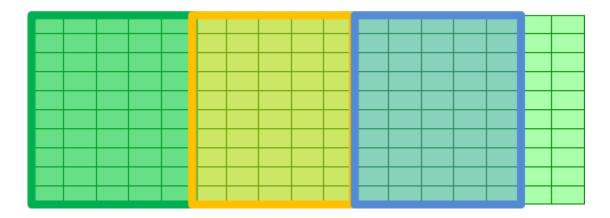


### **Jscop Implementation**

 $Conv[i0,i1,i2,i3] \rightarrow [i0,i1,i2,i3]$ 



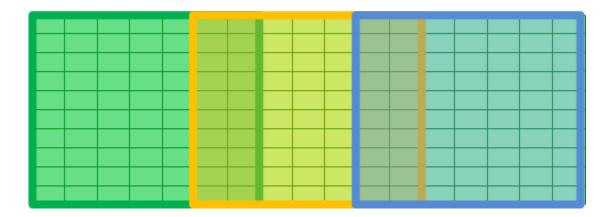
### **Jscop Implementation**



Conv[i0,i1,i2,i3]  $\rightarrow$ [t0,i1,t1,i2,i3] : 0 <= t0 < no\_tiles and 0 <= t1 < tilesize and i0 = tilesize \* t0 + t1



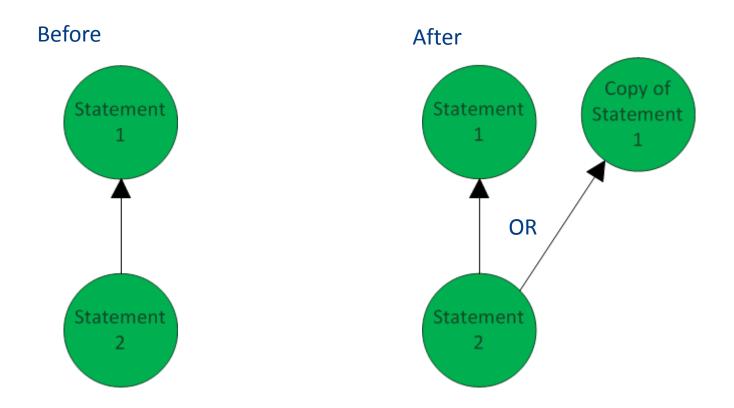
### **Jscop Implementation**



Conv[i0,i1,i2,i3]  $\rightarrow$ [t0,i1,t1,i2,i3] : 0 <= t0 < no\_tiles and 0 <= t1 < tilesize + overlap and i0 = tilesize \* t0 + t1



### **Dependencies**



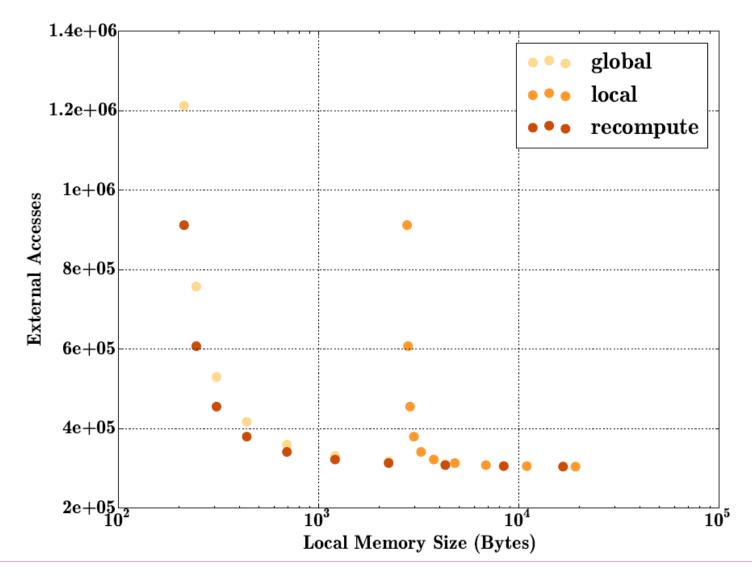
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# Experimental Results

### Where innovation starts

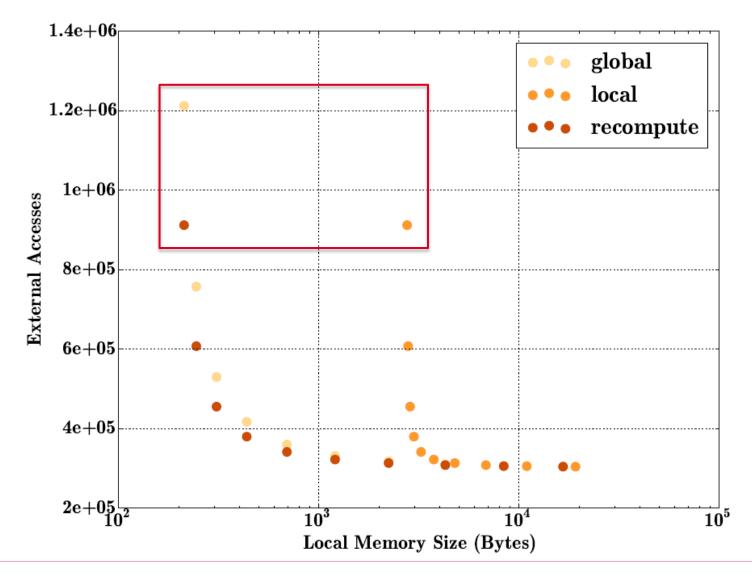


### **Results for different tile sizes**



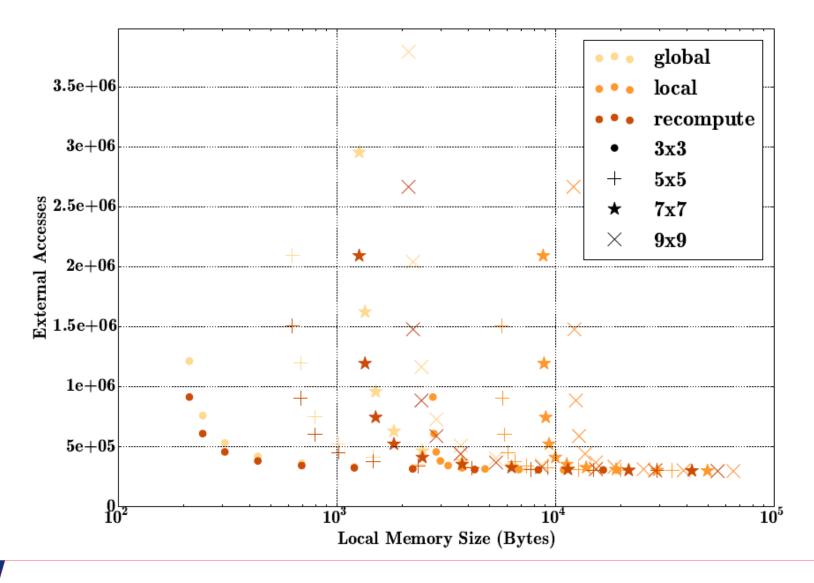


### **Results for different tile sizes**





### **Results for different tile sizes and several kernel sizes**



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# Conclusion and Future Work

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#### Where innovation starts



### Conclusion

- An example CNN application which includes recompute
- Extension of Polly
- Demonstration of the effectiveness of recomputation



### **Future Work**

- Legality Checks
- Model of the effects
- More applications



## And Finally...

- Questions?
- Remarks?
- Suggestions?